

Department of Computer Science

## Course Information Sheet CSCI 4530 Robotics

| <b>Brief Course Description</b><br>(50-words or less)  | This is an introduction to robotics with a focus on autonomous mobile robots.<br>The two major issues dealt with are: (1) cognitive behavior, and (2) motion.<br>Cognitive behavior addresses problem solving using sensory inputs and desired<br>goals. Motion deals with aspects of movement from simple robotic arm<br>movement to autonomous rovers in unknown environments. |  |  |  |  |  |  |
|--|--|--|--|--|--|--|--|
| Extended Course<br>Description / Comments              | This course is cross-listed with ARTI 4530   |  |  |  |  |  |  |
| Pre-Requisites and/or Co-<br>Requisites                | CSCI 2720: Data Structures   |  |  |  |  |  |  |
|  | And Permission of Department   |  |  |  |  |  |  |
| Required, Elective or<br>Selected Elective             | Selected Elective Course   |  |  |  |  |  |  |
| Approved Textbooks                                     | Author(s): Maja Mataric  |  |  |  |  |  |  |
| (if more than one listed, the                          | Title: The Robotics Primer   |  |  |  |  |  |  |
| textbook used is up to the                             | Edition: MIT Press, 2007. 1st  |  |  |  |  |  |  |
| instructor's discretion)                               | ISBN-13: 978-0-262-63354-3   |  |  |  |  |  |  |
|  | Author(s): Siegwart & Nourbakhsh   |  |  |  |  |  |  |
|  | Title: Introduction to Autonomous Mobile Robots  |  |  |  |  |  |  |
|  | Edition: MIT Press, 2 <sup>nd</sup> Edition  |  |  |  |  |  |  |
|  | ISBN-13: 978-0-01535-6   |  |  |  |  |  |  |
| Specific Learning Outcomes<br>(Performance Indicators) | <ol> <li>Students are familiar with constructing small mobile autonomous robots that achieve some goal.</li> <li>Students are familiar with robot control architectures.</li> <li>Students are familiar with the historical development of autonomous mobile robots.</li> <li>Students are familiar with the complexities of constructing autonomous</li> </ol>                  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |

5. Students are familiar with the state-of-the-art of autonomous mobile robotics.

## Relationship Between Student Outcomes and Learning Outcomes

|                      | Student Outcomes |   |   |   |   |   |   |   |   |   |   |
|----------------------|------------------|---|---|---|---|---|---|---|---|---|---|
|                      | a                | b | с | d | e | f | g | h | i | j | k |
|                      |                  | • | • | • |   | • |   | • | • | • | • |
| ng<br>nes            |                  | • | • | • |   | • |   | • | • | • | • |
| Learning<br>Outcomes | •                | • | • | • |   | • |   | • | • | • | • |
| Lei                  |                  | • |   | • |   |   |   | • | • |   |   |
|                      |                  | • | • | • |   | • |   | • | • | • | • |

| <b>Major Topics Covered</b><br>(Approximate Course Hours) | Week1: Introduction and History of Robotics (7.0)     |  |  |  |  |  |
|---|---|--|--|--|--|--|
| 3  credit hours = 37.5  contact                           | Week 3: Robot Control Architectures (7.0)             |  |  |  |  |  |
| 4  credit hours = 50  contact hours                       | Week 5: What Can We Learn From Animal Behavior? (3.5) |  |  |  |  |  |
| Note: Exams count as a major<br>topic covered             | Week 6: What Are Robotic Behaviors? (7.0)             |  |  |  |  |  |
|   | Week 8: Construction Architectures (14.0)             |  |  |  |  |  |
|   | Week 12: Intelligent Behavior (14.0)                  |  |  |  |  |  |
|   | Week 16: Robot Applications (3.5)                     |  |  |  |  |  |
|   | Week 17: Advanced Topics (3.5)                        |  |  |  |  |  |
| <b>Course Master</b>                                      | Dr. Prashant Doshi                                    |  |  |  |  |  |